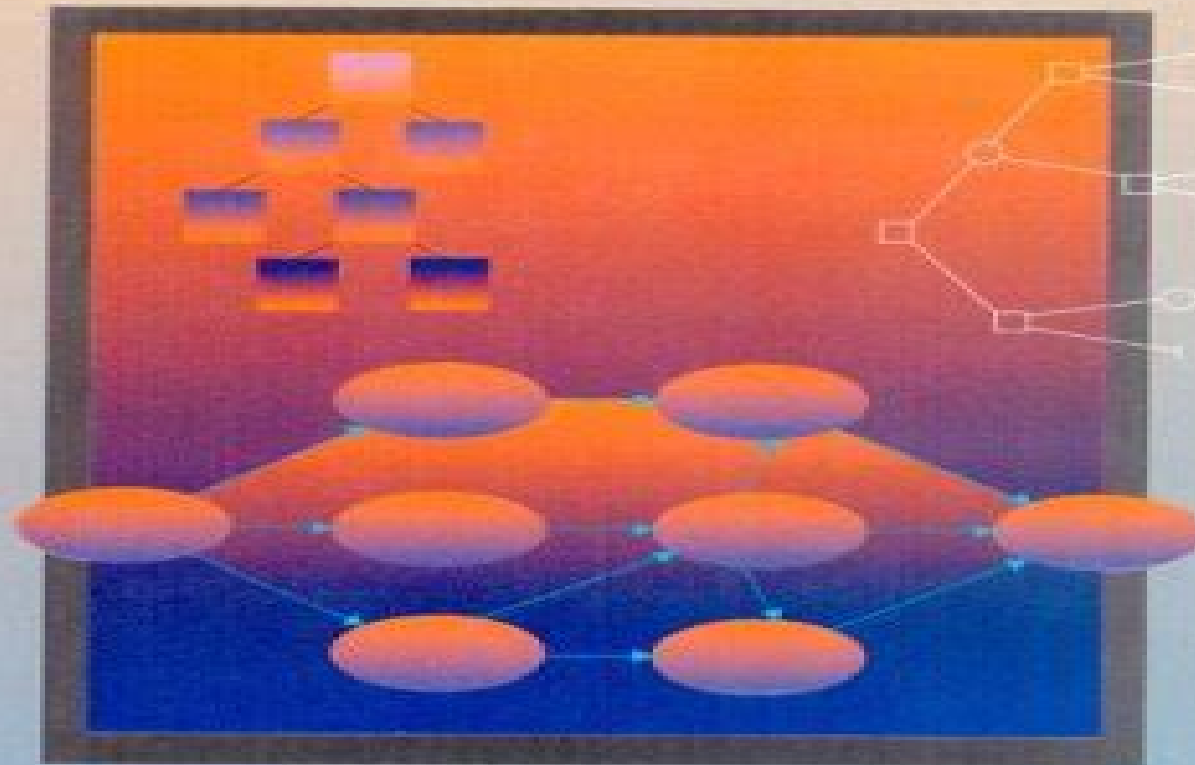


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# Operations Research Applications And Algorithms 4th Edition

**Raul Poler, Josefa Mula, Manuel Díaz-Madroñero, Raquel Sanchis**



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elbow this is the joint between links b and c and it has one degree of freedom actuated by a rc servo motor it can rotate to about 180 by design by link a the motion about the elbow is actuated by a set of gear brains

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