

Jean-Paul Laumond
Naoko Abe *Editors*

Dance Notations and Robot Motion



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Digital Scholarly Editions Beyond Text Tessa Gengnagel, 2024-02-07 Scholarly editions contextualize our cultural heritage. Traditionally methodologies from the field of scholarly editing are applied to works of literature e.g. in order to trace their genesis or present their varied history of transmission. What do we make of the variance in other types of cultural heritage? How can we describe, record and reproduce it systematically? From medieval to modern times, from image to audiovisual media, the book traces discourses across different disciplines in order to develop a conceptual model for scholarly editions on a broader scale. By doing so, it also delves into the theory and philosophy of the digital humanities as such. **Tango Dance and Music** Kendra Stepputat, 2024-01-30 This book is the first to explore tango argentino as translocal practice with a focus on the European context. Beyond that, the book crosses borders in the use of both qualitative and quantitative methods, ranging from participant observation to statistical data evaluation, including optical motion capture for movement analysis. Most of all, it is an important contribution to the emerging field of choreomusicology, focusing on movement and sound structures, dancers and musicians, and the complex relations between all of these factors that all have their share in shaping tango argentino practice. **Dance Notations and Robot Motion** Jean-Paul Laumond, Naoko Abe, 2015-11-24 How and why to write a movement? Who is the writer? Who is the reader? They may be choreographers working with dancers. They may be roboticists programming robots. They may be artists designing cartoons in computer animation. In all such fields, the purpose is to express an intention about a dance, a specific motion, or an action to perform in terms of intelligible sequences of elementary movements as a music score that would be devoted to motion representation. Unfortunately, there is no universal language to write a motion. Motion languages live together in a Babel tower populated by biomechanists, dance notators, neuroscientists, computer scientists, choreographers, roboticists. Each community handles its own concepts and speaks its own language. The book accounts for this diversity. Its origin is a unique workshop held at LAAS CNRS in Toulouse in 2014. Worldwide representatives of various communities met there. Their challenge was to reach a mutual understanding, allowing a choreographer to access robotics concepts or a computer scientist to understand the subtleties of dance notation. The liveliness of this multidisciplinary meeting is reflected by the book, thanks to the willingness of authors to share their own experiences with others. **The ^AOxford Handbook of Improvisation in Dance** Vida L. Midgelow, 2019-02-21 This handbook offers new arguments about the ways that dance improvisation informs understandings of history, socio-cultural conditions, lived experience, and technologies. **Origami\$^{6}\$** Koryo Miura, Toshikazu Kawasaki, Tomohiro Tachi, Ryuhei Uehara, Robert J. Lang, Patsy Wang-Iverson, 2015-12-18 is a unique collection of papers illustrating the connections between origami and a wide range of fields. The papers compiled in this two-part set were presented at the 6th International Meeting on Origami Science, Mathematics, and Education, 10-13 August 2014, Tokyo, Japan. They display the creative melding of origami, or more broadly, folding, with fields ranging from cell biology to space exploration, from education to kinematics, from abstract

mathematical laws to the artistic and aesthetics of sculptural design This two part book contains papers accessible to a wide audience including those interested in art design history and education and researchers interested in the connections between origami and science technology engineering and mathematics Part 1 contains papers on various aspects of mathematics of origami coloring constructibility rigid foldability and design algorithms *The Cumulative Book Index* ,1999

Mathematical Reviews ,2007 *Advances in Modelling and Control of Soft Robots* Concepción A. Monje,Cecilia Laschi,2021-07-14 **American Book Publishing Record** ,2004 *Subject Guide to Books in Print* ,1997 **The British National Bibliography** Arthur James Wells,2006 *Applied Mechanics Reviews* ,1986 *International Books in Print* ,1990 **Forthcoming Books** Rose Arny,2004 *Robotics and Artificial Intelligence in Sports Medicine and Sports Services* Olfa Boubaker,2025-11-01 *Robotics and Artificial Intelligence in Sports Medicine and Sports Services* delves into the latest advancements in sports science medicine and event management The book emphasizes the optimization of athlete performance injury prevention and rehabilitation through emerging technologies It highlights the use of wearable sensors IoT devices AI powered virtual and augmented reality and predictive models based on large language models which are revolutionizing training and recovery strategies Additionally rehabilitation robotics and exoskeletons are enhancing recovery and mobility for clinicians and physiotherapists AI driven drones improve performance monitoring crowd safety and fan engagement while service robots streamline logistics and event management in smart stadiums This book is an invaluable resource for engineers clinicians physiotherapists coaches and policymakers seeking to integrate smart technologies into sports science and medicine Presents advanced technologies in sports medicine rehabilitation and coaching Offers AI for boosting athlete s performance and injury prediction Presents real time monitoring with wearables IoT LLM VR AR fitness trackers and drones Explores exoskeletons and robotics for recovery along with service robots in safe and smart stadiums

Computer Books and Serials in Print ,1985 **Advances in Robotics, 1992** American Society of Mechanical Engineers. Winter Annual Meeting,1992 This volume contains papers presented in the Symposium on Robotics held in the 1992 Winter Annual Meeting of the American Society of Mechanical Engineers ASME **Robot Control 2000 (SYROCO'00)** Peter Kopacek,2001 This Proceedings contains the papers presented at the sixth IFAC Symposium on Robot Control 2000 SYROCO 00 held in Vienna Austria on 21 23 September 2000 The contributions cover the whole field of robot control starting with the classical subjects like non linear robust and hybrid control force and tracking control modelling and identification simulation and education neural and fuzzy control But new robot applications require new robot concepts and new control tasks In consequence most of the contributions deal with mobile intelligent robots and multiple robot systems but also new applications like disassembly One of the fastest growing fields in the last three years is development and control of robots for entertainment leisure and hobby In four survey papers the state of the art in robot control and further developing trends were emphasised Because the field of robotics is growing up today in smaller countries two presentations deal with robots in

Brazil and Macedonia The very important field of sensor fusion and an industrial view of future developments in robot control were also topics of survey papers Intelligent Autonomous Vehicles International Federation of Automatic Control,1993-09-06 There is an increasing range of applications in which a robot has to operate in large unstructured and uncertain environments including military cross country missions fire fighting construction nuclear plant inspections inspecting and repairing subsea structures assembling space stations as well as in intelligent automobiles Uncertainty dominates the problem domain for intelligent autonomous vehicles IAVs through sensing the environment and vehicle state interpreting the data assessing the situation adapting to changes in the environment or tasking replanning navigation and piloting IFAC recognising the industrial technical and economic significance of IAV research established an International Working Party to promote research and dissemination of results in IAV systems The IAV 93 Southampton Workshop and these resulting proceedings exemplify the vitality and significant progress made by leading IAV researchers worldwide

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