

### Question:

An object moves in a straight line according to the equation  $x = 2t^3 - 3t^2 - 6t$ , where  $x$  is in meters and  $t$  is in seconds. At what time is the net Force acting on the object = 0?

- a.  $t = 0.5s$
- b.  $t = 1.0s$
- c.  $t = 2.0s$
- d.  $t = 2.5s$
- e.  $t = 3.0s$

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### Answer:

The correct answer is *a*. The net Force acting on the object will be 0 when the object has zero acceleration, so this question is really asking, "when is the acceleration of this object 0?"

Recall that  $a = \frac{dv}{dt} = \frac{d^2x}{dt^2}$ , so we need to get the second derivative of the  $x$  equation:

$$v = \frac{dx}{dt} = \frac{d}{dt}(2t^3 - 3t^2 - 6t) = 6t^2 - 6t - 6$$

$$a = \frac{dv}{dt} = \frac{d}{dt}(6t^2 - 6t - 6) = 12t - 6$$

$$a = 0 = 12t - 6$$

$$t = 0.5s$$

# Questions With Answer Kinematics

**Boi Faltings**

## Questions With Answer Kinematics:

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**Kinematics of Machinery** Anup Goel,2021-01-01 Kinematics of Machinery is the branch of engineering science which deals with the study of relative motion between the various parts of a machine and the forces which act on them It gives information about the basic concepts and layout of linkages in the assembly of a system or a machine The subject provides information about the principles in analysing the assembly with respect to the displacement velocity and acceleration at any point in a link of a mechanism This book gives technique to find velocity and acceleration of different mechanisms by

graphical and analytical methods. It also includes the basic concepts of toothed gearing and kinematics of gear trains and the effect of friction in motion transmission and in machine components. My hope is that this book through its careful explanations of concepts, practical examples and figures bridges the gap between knowledge and proper application of that knowledge.

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**An Intermediate Course of Mechanics** Alfred William Porter, 1905 **The Dynamics of Flight, The Equations** Jean-Luc Boiffier, 1998-07-27 The Dynamics of Flight The Equations Jean Luc Boiffier SUPA RO and ONERA CERT France The study of aircraft flight is based upon the model formed by the flight dynamics equations which are comprehensively evolved in this book These equations and the associated hypotheses are the fundamental prerequisite of every study of flight dynamics In this work the equations are adapted to the study of the atmospheric or spatial flight of a rigid airplane for which a series of successive simplifications are made ranging from the flat and fixed Earth hypotheses to those of longitudinal decoupling and linearised flight Several representations of the equations are developed with a precise formulation of the atmospheric perturbation influence wind and turbulence The definition of the equilibrium and pseudo equilibrium notions is accompanied by an analytical and numerical general method for equilibrium research Next the linearisation and the decoupling operation fundamental for the dynamic and analytical process of the equations is developed Major features include General equations of flight dynamics with successive simplifications and in several forms calculation details appear in the appendix Precise formulation of atmospheric perturbation on the equations Analytical and numerical methods for equilibrium research and linearisation A compendium of rigorous definitions and notations of the numerous flight dynamics parameters Onboard measures equations Developments designed to solve practical difficulties in a thorough and simple way With its inclusion of both the theoretical and applied aspects of flight dynamics equations this book serves as an essential tool for engineers researchers and students working in the fields of aeronautics flight dynamicists automatic control systems specialists aerodynamicists and specialists in structures [Kinematics of the Gait of an Individual Running with a Below the Knee Amputation Wearing the Flex-foot \(TM\) and the Sach-Foot](#) Doreen Marie Espinoza, 1998

[Computational Kinematics '95](#) J.-P. Merlet, Bahram Ravani, 1995 The trends and progress attained in computational

kinematics over a broad class of problems are grouped into six parts describing the main themes kinematics algorithms discussing kinematics problems in light of their solution algorithms kinematics of mechanisms studying problems related to specific mechanisms singularities workspace discussing the determination of the workspace of given mechanisms parallel manipulators and motion and grasp planning touching on computational geometry The volume contains a representative sample of the most modern techniques available for kinematics problems including techniques based on advances in algebraic geometry Researchers graduate students and practising engineers in work relating to kinematics robotics machine design and computer science should find this work useful

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