Yu Sun
Aman Behal
Chi–Kit Ronald Chung   *Editors*

New Development in Robot Vision

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New Development In Robot Vision Cognitive Systems Monographs:

New Development in Robot Vision Yu Sun,Aman Behal,Chi-Kit Ronald Chung,2014-09-26 The field of robotic vision has advanced dramatically recently with the development of new range sensors Tremendous progress has been made resulting in significant impact on areas such as robotic navigation scene environment understanding and visual learning This edited book provides a solid and diversified reference source for some of the most recent important advancements in the field of robotic vision The book starts with articles that describe new techniques to understand scenes from 2D 3D data such as estimation of planar structures recognition of multiple objects in the scene using different kinds of features as well as their spatial and semantic relationships generation of 3D object models approach to recognize partially occluded objects etc Novel techniques are introduced to improve 3D perception accuracy with other sensors such as a gyroscope positioning accuracy with a visual servoing based alignment strategy for microassembly and increasing object recognition reliability using related manipulation motion models For autonomous robot navigation different vision based localization and tracking strategies and algorithms are discussed New approaches using probabilistic analysis for robot navigation online learning of vision based robot control and 3D motion estimation via intensity differences from a monocular camera are described This collection will be beneficial to graduate students researchers and professionals working in the area of robotic vision   Cognitive Robotics Angelo Cangelosi,Minoru Asada,2022-05-17 The current state of the art in cognitive robotics covering the challenges of building AI powered intelligent robots inspired by natural cognitive systems A novel approach to building AI powered intelligent robots takes inspiration from the way natural cognitive systems in humans animals and biological systems develop intelligence by exploiting the full power of interactions between body and brain the physical and social environment in which they live and phylogenetic developmental and learning dynamics This volume reports on the current state of the art in cognitive robotics offering the first comprehensive coverage of building robots inspired by natural cognitive systems Contributors first provide a systematic definition of cognitive robotics and a history of developments in the field They describe in detail five main approaches developmental neuro evolutionary swarm and soft robotics They go on to consider methodologies and concepts treating topics that include commonly used cognitive robotics platforms and robot simulators biomimetic skin as an example of a hardware based approach machine learning methods and cognitive architecture Finally they cover the behavioral and cognitive capabilities of a variety of models experiments and applications looking at issues that range from intrinsic motivation and perception to robot consciousness Cognitive Robotics is aimed at an interdisciplinary audience balancing technical details and examples for the computational reader with theoretical and experimental findings for the empirical scientist   Developmental Robotics Angelo Cangelosi,Matthew Schlesinger,2015-01-09 A comprehensive overview of an interdisciplinary approach to robotics that takes direct inspiration from the developmental and learning phenomena observed in children s cognitive development Developmental robotics is a collaborative and interdisciplinary

approach to robotics that is directly inspired by the developmental principles and mechanisms observed in children s cognitive development It builds on the idea that the robot using a set of intrinsic developmental principles regulating the real time interaction of its body brain and environment can autonomously acquire an increasingly complex set of sensorimotor and mental capabilities This volume drawing on insights from psychology computer science linguistics neuroscience and robotics offers the first comprehensive overview of a rapidly growing field After providing some essential background information on robotics and developmental psychology the book looks in detail at how developmental robotics models and experiments have attempted to realize a range of behavioral and cognitive capabilities The examples in these chapters were chosen because of their direct correspondence with specific issues in child psychology research each chapter begins with a concise and accessible overview of relevant empirical and theoretical findings in developmental psychology The chapters cover intrinsic motivation and curiosity motor development examining both manipulation and locomotion perceptual development including face recognition and perception of space social learning emphasizing such phenomena as joint attention and cooperation language from phonetic babbling to syntactic processing and abstract knowledge including models of number learning and reasoning strategies Boxed text offers technical and methodological details for both psychology and robotics experiments **Re-Enacting Sensorimotor Experience for Cognition** Guido Schillaci,Verena V. Hafner,Bruno Lara,2017-03-29 Mastering the sensorimotor capabilities of our body is a skill that we acquire and refine over time starting at the prenatal stages of development This learning process is linked to brain development and is shaped by the rich set of multimodal information experienced while exploring and interacting with the environment Evidence coming from neuroscience suggests the brain forms and mantains body representations as the main strategy to this mastering Although it is still not clear how this knowledge is represented in our brain it is reasonable to think that such internal models of the body undergo a continuous process of adaptation They need to match growing corporal dimensions during development as well as temporary changes in the characteristics of the body such as the transient morphological alterations produced by the usage of tools In the robotics community there is an increasing interest in reproducing similar mechanisms in artificial agents mainly motivated by the aim of producing autonomous adaptive systems that can deal with complexity and uncertainty in human environments Although promising results have been achieved in the context of sensorimotor learning and autonomous generation of body representations it is still not clear how such low level representations can be scaled up to more complex motor skills and how they can enable the development of cognitive capabilities Recent findings from behavioural and brain studies suggests that processes of mental simulations of action perception loops are likely to be executed in our brain and are dependent on internal motor representations The capability to simulate sensorimotor experience might represent a key mechanism behind the implementation of further cognitive skills such as self detection self other distinction and imitation Empirical investigation on the functioning of similar processes in the brain and on their implementation in artificial agents is

fragmented This e book comprises a collection of manuscripts published by Frontiers in Robotics and Artificial Intelligence under the section Humanoid Robotics on the research topic re enactment of sensorimotor experience for cognition in artificial agents This compendium aims at condensing the latest theoretical review and experimental studies that address new paradigms for learning and integrating multimodal sensorimotor information in artificial agents re use of the sensorimotor experience for cognitive development and further construction of more complex strategies and behaviours using these concepts The authors would like to thank M A Dylan Andrade for his art work for the cover **Visual Perception for Humanoid Robots** David Israel González Aguirre,2018-09-01 This book provides an overview of model based environmental visual perception for humanoid robots The visual perception of a humanoid robot creates a bidirectional bridge connecting sensor signals with internal representations of environmental objects The objective of such perception systems is to answer two fundamental questions What where is it To answer these questions using a sensor to representation bridge coordinated processes are conducted to extract and exploit cues matching robot s mental representations to physical entities These include sensor actuator modeling calibration filtering and feature extraction for state estimation This book discusses the following topics in depth Active Sensing Robust probabilistic methods for optimal high dynamic range image acquisition are suitable for use with inexpensive cameras This enables ideal sensing in arbitrary environmental conditions encountered in human centric spaces The book quantitatively shows the importance of equipping robots with dependable visual sensing Feature Extraction Recognition Parameter free edge extraction methods based on structural graphs enable the representation of geometric primitives effectively and efficiently This is done by eccentricity segmentation providing excellent recognition even on noisy low resolution images Stereoscopic vision Euclidean metric and graph shape descriptors are shown to be powerful mechanisms for difficult recognition tasks Global Self Localization Depth Uncertainty Learning Simultaneous feature matching for global localization and 6D self pose estimation are addressed by a novel geometric and probabilistic concept using intersection of Gaussian spheres The path from intuition to the closed form optimal solution determining the robot location is described including a supervised learning method for uncertainty depth modeling based on extensive ground truth training data from a motion capture system The methods and experiments are presented in self contained chapters with comparisons and the state of the art The algorithms were implemented and empirically evaluated on two humanoid robots ARMAR III A B The excellent robustness performance and derived results received an award at the IEEE conference on humanoid robots and the contributions have been utilized for numerous visual manipulation tasks with demonstration at distinguished venues such as ICRA CeBIT IAS and Automatica *Toward Robotic Socially Believable Behaving Systems - Volume I* Anna Esposito,Lakhmi C. Jain,2016-03-21 This volume is a collection of research studies on the modeling of emotions in complex autonomous systems Several experts in the field are reporting their efforts and reviewing the literature in order to shed lights on how the processes of coding and decoding emotional states took place in humans

which are the physiological physical and psychological variables involved invent new mathematical models and algorithms to describe them and motivate these investigations in the light of observable societal changes and needs such as the aging population and the cost of health care services The consequences are the implementation of emotionally and socially believable machines acting as helpers into domestic spheres where emotions drive behaviors and actions The contents of the book are highly multidisciplinary since the modeling of emotions in robotic socially believable systems requires a holistic perspective on topics coming from different research domains such as computer science engineering sociology psychology linguistic and information communication The book is of interest both to experts and students since last research works on a so complex multidisciplinary topic are described in a neat and didactical scientific language *Handbook of Child Psychology, Cognition, Perception, and Language* William Damon,Richard M. Lerner,2006-03-31 Publisher Description **Documentation Abstracts** ,1993 **Toward a Unified Theory of Development** John P. Spencer,Michael S. C. Thomas,James L. McClelland,2009 From William James to Sigmund Freud to Jean Piaget to B F Skinner scholars and parents have wondered how children move from the blooming buzzing confusion of infancy through the tumult of childhood and adolescence into adulthood Does development occur continuously over time or in a series of dramatic stages Is development driven by learning or by biological maturational processes What is the nature of experience and how does it generate change The study of development has always been organized around these big questions And answers to these questions have a profound influence on daily life forming a framework for how parents think about their own children and influencing both national policy and educational curricula This book defines and refines two major theoretical approaches within developmental science that address the central issues of development connectionism and dynamical systems theory Spencer Thomas and McClelland have brought together chapters that provide an introduction overview and critical evaluation of each approach including three sets of case studies that illustrate how both approaches have been used to study topics ranging from early motor development to the acquisition of grammar They also present a collection of commentaries by leading scholars which offer a critical view from both anoutsiders s and an insider s perspective The book is unique in the range of its treatment it begins to delineate how developmental science can incorporate advances within neuroscience and computational modeling and brings the new ideas of connectionism and dynamic systems theory into sharper focus clarifying their usefulness and explanatory power **A Roadmap for Cognitive Development in Humanoid Robots** David Vernon,Claes von Hofsten,Luciano Fadiga,2011-12-28 This book addresses the central role played by development in cognition The focus is on applying our knowledge of development in natural cognitive systems specifically human infants to the problem of creating artificial cognitive systems in the guise of humanoid robots The approach is founded on the three fold premise that a cognition is the process by which an autonomous self governing agent acts effectively in the world in which it is embedded b the dual purpose of cognition is to increase the agent s repertoire of effective actions and its power to anticipate the need for

future actions and their outcomes and c development plays an essential role in the realization of these cognitive capabilities Our goal in this book is to identify the key design principles for cognitive development We do this by bringing together insights from four areas enactive cognitive science developmental psychology neurophysiology and computational modelling This results in roadmap comprising a set of forty three guidelines for the design of a cognitive architecture and its deployment in a humanoid robot The book includes a case study based on the iCub an open systems humanoid robot which has been designed specifically as a common platform for research on embodied cognitive systems **Aerospace Medicine and Biology** ,1991 **The Child with Physical Disability** ,1991 **The Zoological Record** ,2002 *Handbook of Learning and Cognitive Processes* William Kaye Estes,1978 **Subject Guide to Books in Print** ,1997 **Linguistics and Language Behavior Abstracts** ,1985 *Subject Guide to Children's Books in Print 1997* Bowker Editorial Staff,R R Bowker Publishing,1996-09 International Books in Print ,1990 Artificial Intelligence And Natural Man Margaret A. Boden,1987-05-10 Not for sale in the U S and Canada *Resources in Education* ,1987

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