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Medicine and Sports Services Olfa Boubaker, 2025-11-01 Robotics and Artificial Intelligence in Sports Medicine and Sports Services delves into the latest advancements in sports science medicine and event management. The book emphasizes the optimization of athlete performance, injury prevention and rehabilitation through emerging technologies. It highlights the use of wearable sensors, IoT devices, AI-powered virtual and augmented reality, and predictive models based on large language models which are revolutionizing training and recovery strategies. Additionally, rehabilitation robotics and exoskeletons are enhancing recovery and mobility for clinicians and physiotherapists. AI-driven drones improve performance monitoring, crowd safety, and fan engagement while service robots streamline logistics and event management in smart stadiums. This book is an invaluable resource for engineers, clinicians, physiotherapists, coaches, and policymakers seeking to integrate smart technologies into sports science and medicine. Presents advanced technologies in sports medicine, rehabilitation, and coaching. Offers AI for boosting athlete's performance and injury prediction. Presents real-time monitoring with wearables, IoT, LLM, VR, AR, fitness trackers, and drones. Explores exoskeletons and robotics for recovery along with service robots in safe and smart stadiums.

Mechatronics for Complex Products and Systems Zhuming Bi, 2025-02-12 A project-based approach to designing mechatronic systems with new and emerging technologies. In Mechatronics for Complex Products and Systems: Project-Based Designs for Cyber Physical Systems, Digital Twins, and Other Emerging Technologies, distinguished researcher Dr. Zhuming Bi delivers an expert discussion of real-world mechatronics skills that students will need in their engineering careers. The book explains the characteristics and innovation principles underlying mechatronic systems, including modularization, adaptability, predictability, sustainability, and concurrent engineering. A mechatronic system is decomposed into a set of mechatronic functional modules such as power systems, actuating systems, sensing systems, systems of signal conditioning and processing, and control systems. The author also offers a thorough introduction from classic integration of mechanical, electronic, and electrical systems to more complex products and systems, including cyber physical systems, robotics, human-robot interactions, digital twins, and Internet of Things applications. Insightful project assignments that help reinforce a practical understanding of a learning subject. Practical discussions of real-world engineering problems. Comprehensive guidance on how to select the right type of sensors, motors, and controllers for a variety of mechatronic functional modules. Perfect for advanced undergraduate and graduate students of mechatronics. Mechatronics for Complex Products and Systems will also benefit professional engineers working on interdisciplinary projects enabled by digital technologies, Internet of Things, IoT, and Artificial Intelligence, AI.

Advances in Modelling and Control of Soft Robots

Concepción A. Monje, Cecilia Laschi, 2021-07-14

The art of human-robot interaction: Creative perspectives from

design and the arts Damith C. Herath,Elizabeth Ann Jochum,Christian Kroos,David St-Onge,2023-03-01 **Software Architectures for Humanoid Robotics** Lorenzo Natale,Tamim Asfour,Fumio Kanehiro,Nikolaus Vahrenkamp,2018-10-11

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kinematically redundant to over constrained The book brings together 43 peer reviewed papers They report on the latest scientific and applied achievements The main theme that connects them is the movement of robots in the most diverse areas of application *Advances in Robot Kinematics* Jadran Lenarčič,Oussama Khatib,2014-05-19 The topics addressed in this book cover the whole range of kinematic analysis synthesis and design and consider robotic systems possessing serial parallel and cable driven mechanisms The robotic systems range from being less than fully mobile to kinematically redundant to over constrained The fifty six contributions report the latest results in robot kinematics with emphasis on emerging areas such as design and control of humanoids or humanoid subsystems The book is of interest to researchers wanting to bring their knowledge up to date regarding modern topics in one of the basic disciplines in robotics which relates to the essential property of robots the motion of mechanisms *Advances in Robot Kinematics 2022* Oscar Altuzarra,Andrés

Kecskeméthy,2022-06-17 This book reports on the latest scientific achievements on robot kinematics provided by the prominent researchers participating in the 18th International Symposium on Advances in Robot Kinematics ARK2022 organized in the University of the Basque Country Bilbao Spain It is of interest to researchers wanting to know more about the latest topics and methods in the fields of the kinematics control and design of robotic systems The book brings together 53 peer reviewed papers These cover the full range of robotic systems including serial parallel flexible mechanisms and cable driven manipulators and tackle problems such as kinematic analysis of robots robot modelling and simulation theories and methods in kinematics singularity analysis kinematic problems in parallel robots redundant robots cable robots kinematics in biological systems flexible parallel manipulators humanoid robots and humanoid subsystems *Modelling and Control of Robot Manipulators* Lorenzo Sciavicco,Bruno Siciliano,2001-02-19 Fundamental and technological topics are blended uniquely and developed clearly in nine chapters with a gradually increasing level of complexity A wide variety of relevant problems is raised throughout and the proper tools to find engineering oriented solutions are introduced and explained step by step Fundamental coverage includes Kinematics Statics and dynamics of manipulators Trajectory planning and motion control in free space Technological aspects include Actuators Sensors Hardware software control architectures Industrial robot control algorithms Furthermore established research results involving description of end effector orientation closed kinematic chains kinematic redundancy and singularities dynamic parameter identification robust and adaptive control and force motion control are provided To provide readers with a homogeneous background three appendices are included on Linear algebra Rigid body mechanics Feedback control To acquire practical skill more than 50 examples and case studies are carefully worked out and interwoven through the text with frequent resort to simulation In addition more than 80 end of chapter exercises are proposed and the book is accompanied by a solutions manual containing the MATLAB code for computer problems this is available from the publisher free of charge to those adopting this work as a textbook for courses

Advances in Robot Kinematics 2016 Jadran Lenarčič,Jean-Pierre Merlet,2018-08-07 This book brings together 46 peer

reviewed papers that are of interest to researchers wanting to know more about the latest topics and methods in the fields of the kinematics control and design of robotic systems. These papers cover the full range of robotic systems including serial parallel and cable driven manipulators both planar and spatial. The systems range from being less than fully mobile to kinematically redundant to over constrained. In addition to these more familiar areas the book also highlights recent advances in some emerging areas such as the design and control of humanoids and humanoid subsystems the analysis modeling and simulation of human body motions mobility analyses of protein molecules and the development of machines that incorporate man. **Advances in Robot Kinematics 2024** Jadran Lenarčič, Manfred Hustý, 2024-07-02. This book is aimed at researchers specializing in the kinematics of robot mechanisms as well as at doctoral students in guiding their research work. A spectrum of the latest achievements in kinematics analysis modelling simulation design and control is covered. New theories and methods are applied to serial parallel and cable driven mechanisms for use in industrial or service robotics. The systems range from being less than fully mobile to kinematically redundant and over constrained. Forty nine papers are included arranged in seven chapters as presented at the 19th Symposium on Advances in Robot Kinematics 2024. The symposium which has been held since 1988 was organized this time in Ljubljana Slovenia where it began thirty six years ago. The papers have been rigorously selected based on peer review and are arranged in chapters randomly as is the prevailing tradition of these symposia. In doing so we aim to give equal emphasis to each of these achievements.

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