

Nonlinear System Identification



Nonlinear System Identification Nonlinear System Identification

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Nonlinear System Identification Nonlinear System Identification:

Nonlinear system identification. 2. Nonlinear system structure identification Robert Haber,László Keviczky,1999 This is the second part of a two volume handbook presenting a comprehensive overview of nonlinear dynamic system identification The books include many aspects of nonlinear processes such as modelling parameter estimation structure search nonlinearity and model validity tests

Nonlinear System Identification Oliver Nelles,2013-03-09 Written from an engineering point of view this book covers the most common and important approaches for the identification of nonlinear static and dynamic systems The book also provides the reader with the necessary background on optimization techniques making it fully self contained The new edition includes exercises

Nonlinear System Identification — Input-Output Modeling Approach Robert Haber,L. Keviczky,1999-07-31 The subject of the book is to present the modeling parameter estimation and other aspects of the identification of nonlinear dynamic systems The treatment is restricted to the input output modeling approach Because of the widespread usage of digital computers discrete time methods are preferred Time domain parameter estimation methods are dealt with in detail frequency domain and power spectrum procedures are described shortly The theory is presented from the engineering point of view and a large number of examples of case studies on the modeling and identifications of real processes illustrate the methods Almost all processes are nonlinear if they are considered not merely in a small vicinity of the working point To exploit industrial equipment as much as possible mathematical models are needed which describe the global nonlinear behavior of the process If the process is unknown or if the describing equations are too complex the structure and the parameters can be determined experimentally which is the task of identification The book is divided into seven chapters dealing with the following topics 1 Nonlinear dynamic process models 2 Test signals for identification 3 Parameter estimation methods 4 Nonlinearity test methods 5 Structure identification 6 Model validity tests 7 Case studies on identification of real processes Chapter I summarizes the different model descriptions of nonlinear dynamical systems

Block-oriented Nonlinear System Identification Fouad Giri,Er-Wei Bai,2010-08-18 Block oriented Nonlinear System Identification deals with an area of research that has been very active since the turn of the millennium The book makes a pedagogical and cohesive presentation of the methods developed in that time These include iterative and over parameterization techniques stochastic and frequency approaches support vector machine subspace and separable least squares methods blind identification method bounded error method and decoupling inputs approach The identification methods are presented by authors who have either invented them or contributed significantly to their development All the important issues e g input design persistent excitation and consistency analysis are discussed The practical relevance of block oriented models is illustrated through biomedical physiological system modelling The book will be of major interest to all those who are concerned with nonlinear system identification whatever their activity areas This is particularly the case for educators in electrical mechanical chemical and biomedical engineering and for practising engineers in process aeronautic

aerospace robotics and vehicles control Block oriented Nonlinear System Identification serves as a reference for active researchers new comers industrial and education practitioners and graduate students alike *Nonlinear System Identification* Oliver Nelles, 2020-09-09 This book provides engineers and scientists in academia and industry with a thorough understanding of the underlying principles of nonlinear system identification It equips them to apply the models and methods discussed to real problems with confidence while also making them aware of potential difficulties that may arise in practice Moreover the book is self contained requiring only a basic grasp of matrix algebra signals and systems and statistics Accordingly it can also serve as an introduction to linear system identification and provides a practical overview of the major optimization methods used in engineering The focus is on gaining an intuitive understanding of the subject and the practical application of the techniques discussed The book is not written in a theorem proof style instead the mathematics is kept to a minimum and the ideas covered are illustrated with numerous figures examples and real world applications In the past nonlinear system identification was a field characterized by a variety of ad hoc approaches each applicable only to a very limited class of systems With the advent of neural networks fuzzy models Gaussian process models and modern structure optimization techniques a much broader class of systems can now be handled Although one major aspect of nonlinear systems is that virtually every one is unique tools have since been developed that allow each approach to be applied to a wide variety of systems

Identification of Dynamic Systems Rolf Isermann, Marco Münchhof, 2010-11-22 Precise dynamic models of processes are required for many applications ranging from control engineering to the natural sciences and economics Frequently such precise models cannot be derived using theoretical considerations alone Therefore they must be determined experimentally This book treats the determination of dynamic models based on measurements taken at the process which is known as system identification or process identification Both offline and online methods are presented i e methods that post process the measured data as well as methods that provide models during the measurement The book is theory oriented and application oriented and most methods covered have been used successfully in practical applications for many different processes Illustrative examples in this book with real measured data range from hydraulic and electric actuators up to combustion engines Real experimental data is also provided on the Springer webpage allowing readers to gather their first experience with the methods presented in this book Among others the book covers the following subjects determination of the non parametric frequency response fast Fourier transform correlation analysis parameter estimation with a focus on the method of Least Squares and modifications identification of time variant processes identification in closed loop identification of continuous time processes and subspace methods Some methods for nonlinear system identification are also considered such as the Extended Kalman filter and neural networks The different methods are compared by using a real three mass oscillator process a model of a drive train For many identification methods hints for the practical implementation and application are provided The book is intended to meet the needs of students and practicing engineers working in

research and development design and manufacturing

Nonlinear system identification. 1. Nonlinear system parameter identification Robert Haber, László Keviczky, 1999 The first of two volumes this handbook presents a

comprehensive overview of nonlinear dynamic system parameter identification The volumes cover many aspects of nonlinear processes including modelling parameter estimation structure search nonlinearity and model validity tests

Nonlinear System Identification Oliver Nelles, 2001 Written from an engineering point of view this book covers the most common and important approaches for the identification of nonlinear static and dynamic systems The book also provides the reader with the necessary background on optimization techniques making it fully self contained The new edition includes exercises

Adaptive Nonlinear System Identification Tokunbo Ogunfunmi, 2008-11-01 Focuses on System Identification applications of the adaptive methods presented but which can also be applied to other applications of adaptive nonlinear processes

Covers recent research results in the area of adaptive nonlinear system identification from the authors and other researchers in the field

Nonlinear System Identification Stephen A. Billings, 2013-07-29 Nonlinear System Identification NARMAX Methods in the Time Frequency and Spatio Temporal Domains describes a comprehensive framework for the identification and analysis of nonlinear dynamic systems in the time frequency and spatio temporal domains This book is written with an emphasis on making the algorithms accessible so that they can be applied and used in practice Includes coverage of The NARMAX nonlinear autoregressive moving average with exogenous inputs model The orthogonal least squares algorithm that allows models to be built term by term where the error reduction ratio reveals the percentage contribution of each model term Statistical and qualitative model validation methods that can be applied to any model class Generalised frequency response functions which provide significant insight into nonlinear behaviours A completely new class of filters that can move split spread and focus energy The response spectrum map and the study of sub harmonic and severely nonlinear systems Algorithms that can track rapid time variation in both linear and nonlinear systems The important class of spatio temporal systems that evolve over both space and time Many case study examples from modelling space weather through identification of a model of the visual processing system of fruit flies to tracking causality in EEG data are all included to demonstrate how easily the methods can be applied in practice and to show the insight that the algorithms reveal even for complex systems NARMAX algorithms provide a fundamentally different approach to nonlinear system identification and signal processing for nonlinear systems NARMAX methods provide models that are transparent which can easily be analysed and which can be used to solve real problems This book is intended for graduates postgraduates and researchers in the sciences and engineering and also for users from other fields who have collected data and who wish to identify models to help to understand the dynamics of their systems

Nonlinear system identification : a state-space approach Vincent Verdult, 2002

Adaptive Nonlinear System Identification Tokunbo Ogunfunmi, 2007-09-05 Focuses on System Identification applications of the adaptive methods presented but which can also be applied to other applications of adaptive nonlinear

processes Covers recent research results in the area of adaptive nonlinear system identification from the authors and other researchers in the field **System Identification for Structured Nonlinear Systems** Mareike Silke Claassen,2001

Nonlinear System Analysis and Identification from Random Data Julius S. Bendat,1990-03-16 Describes procedures to identify and analyze the properties of many types of nonlinear systems from random data measured at the input and output points of physical systems Improvements are offered in applying older techniques and problems that traditionally have been difficult to analyze are solved by new simpler procedures Formulas are stated for optimum nonlinear system identification in both general models consisting of parallel linear bilinear and trilinear systems and special models consisting of parallel linear finite memory square law systems and finite memory cubic systems New results obtained here show when and how to replace complicated single input output nonlinear models with simpler alternative multiple input single output linear models New error analysis formulas are presented to design experiments and to evaluate estimates obtained from measured data Includes many illustrative examples *System Identification With Matlab* A. Smith,2017-11-19 This book develops the work with Nonlinear Models and Time Series Identification To represent nonlinear system dynamics you can estimate Hammerstein Wiener models and nonlinear ARX models with wavelet network tree partition and sigmoid network nonlinearities MATLAB System Identification Toolbox performs grey box system identification for estimating parameters of a user defined model You can use the identified model for system response prediction and plant modeling in Simulink The toolbox also supports time series data modeling and time series forecasting It is possible to analyze time series data by identifying linear and nonlinear models including AR ARMA and state space models forecast values The most important content that this book provides are the following When to Fit Nonlinear Models Nonlinear Model Estimation Nonlinear Model Structures Nonlinear ARX Models Hammerstein Wiener Models Nonlinear Grey Box Models Preparing Data for Nonlinear Identification Identifying Nonlinear ARX Models Prepare Data for Identification Configure Nonlinear ARX Model Structure Specify Estimation Options for Nonlinear ARX Models Initialize Nonlinear ARX Estimation Using Linear Model Estimate Nonlinear ARX Models in the App Estimate Nonlinear ARX Models at the Command Line Estimate Nonlinear ARX Models Initialized Using Linear ARX Models Validate Nonlinear ARX Models Using Nonlinear ARX Models Linear Approximation of Nonlinear Black Box Models Nonlinear Black Box Model Identification Identifying Hammerstein Wiener Models Available Nonlinearity Estimators for Hammerstein Wiener Models Estimate Hammerstein Wiener Models in the App Estimate Hammerstein Wiener Models at the Command Line Validating Hammerstein Wiener Models How the Software Computes Hammerstein Wiener Model Output Evaluating Nonlinearities SISO Evaluating Nonlinearities MIMO Simulation of Hammerstein Wiener Model Estimate Hammerstein Wiener Models Initialized Using Linear OE Models Estimate Linear Grey Box Models Estimate Continuous Time Grey Box Model for Heat Diffusion Estimate Discrete Time Grey Box Model with Parameterized Disturbance Estimate Coefficients of ODEs to Fit Given Solution Estimate Model Using Zero Pole Gain

Parameters Estimate Nonlinear Grey Box Models Identifying State Space Models with Separate Process and Measurement Noise Descriptions Time Series Identification Preparing Time Series Data Estimate Time Series Power Spectra Estimate AR and ARMA Models Definition of AR and ARMA Models Estimating Polynomial Time Series Models in the App Estimating AR and ARMA Models at the Command Line Estimate State Space Time Series Models Identify Time Series Models at the Command Line Estimate ARIMA Models Analyze Time Series Models Introduction to Forecasting of Dynamic System Response Forecasting Time Series Using Linear Models Forecasting Response of Linear Models with Exogenous Inputs Forecasting Response of Nonlinear Models Forecast the Output of a Dynamic System Forecast Time Series Data Using an ARMA Model Recursive Model Identification *Mastering System Identification in 100 Exercises* Johan Schoukens, Rik Pintelon, Yves Rolain, 2012-04-02 This book enables readers to understand system identification and linear system modeling through 100 practical exercises without requiring complex theoretical knowledge The contents encompass state of the art system identification methods with both time and frequency domain system identification methods covered including the pros and cons of each Each chapter features MATLAB exercises discussions of the exercises accompanying MATLAB downloads and larger projects that serve as potential assignments in this learn by doing resource **Nonlinear System Identification Study. Part I. Implementation Feasibility Study** E. J. Ewen, GENERAL ELECTRIC CO UTICA N Y AIRCRAFT EQUIPMENT DIV., 1979 The implementation feasibility of a nonlinear system identification technique is evaluated in this report The identification technique uses a black box approach requiring measurements only at system input and output terminals and is applicable to weakly nonlinear systems whose behavior is adequately characterized by a finite Volterra series Three hardware implementations of the identification technique are postulated and their respective performances are evaluated The impact of A/D converter quantization error non ideal amplifiers multipliers and integrators on performance of the identification process is assessed Performance requirements for each of the three implementations are derived via simulation and analysis The feasibility of implementing the technique using commercially available state of the art components and measurement equipment in each implementation is assessed RADCR 79 199 Part II A computational complexity study of the identification technique processing to determine the class of nonlinear systems to which the technique can be practically applied will be published at a later date Author **System Identification with MATLAB. Nonlinear Models, Odes and Time Series** Marvin L., 2016-10-23 In System Identification Toolbox software MATLAB represents linear systems as model objects Model objects are specialized data containers that encapsulate model data and other attributes in a structured way Model objects allow you to manipulate linear systems as single entities rather than keeping track of multiple data vectors matrices or cell arrays Model objects can represent single input single output SISO systems or multiple input multiple output MIMO systems You can represent both continuous and discrete time linear systems This book develops the next task with models Nonlinear Black Box Model Identification Nonlinear Model Identification Fit

Nonlinear Models Identifying Nonlinear ARX Models Nonlinearity Estimators for Nonlinear ARX Models Estimate Nonlinear ARX Models in the GUI Estimate Nonlinear ARX Models at the Command Line Validating Nonlinear ARX Models Identifying Hammerstein Wiener Models Nonlinearity Estimators for Hammerstein Wiener Models Estimation Algorithm for Hammerstein Wiener Models Validating Hammerstein Wiener Models Linear Approximation of Nonlinear Black Box Models ODE Parameter Estimation Grey Box Modeling Estimating Linear Grey Box Models Estimating Nonlinear Grey Box Models After Estimating Grey Box Models Estimating Coefficients of ODEs to Fit Given Solution Estimate Model Using Zero Pole Gain Parameters Time Series Identification Estimating Time Series Power Spectra Estimate Time Series Power Spectra Using the GUI Estimate Time Series Power Spectra at the Command Line Estimating AR and ARMA Models Estimating Polynomial Time Series Models in the GUI Estimating AR and ARMA Models at the Command Line Estimating State Space Time Series Models Estimating State Space Models at the Command Line Identify Time Series Models at Command Line Estimating Nonlinear Models for Time Series Data Estimating ARIMA Models Analyzing of Time Series Models Recursive Model Identification General Form of Recursive Estimation Algorithm Kalman Filter Algorithm Recursive Estimation and Data Segmentation Techniques in System Identification Toolbox Model Analysis Validating Models After Estimation Plotting Models in the GUI Simulating and Predicting Model Output Simulation and Prediction in the GUI Simulation and Prediction at the Command Line Predict Using Time Series Model Residual Analysis Impulse and Step Response Plots Frequency Response Plots Displaying the Confidence Interval Noise Spectrum Plots Pole and Zero Plots Analyzing MIMO Models Akaike's Criteria for Model Validation Troubleshooting Models Unstable Models Missing Input Variables Complicated Nonlinearities Spectrum Estimation Using Complex Data System Identification Toolbox Blocks Using System Identification Toolbox Blocks in Simulink Models Identifying Linear Models Simulating Identified Model Output in Simulink Simulate Identified Model Using Simulink Software System Identification Tool GUI

An Intelligent Nonlinear System Identification Method with an Application to Condition Monitoring Clara Echavarria, 2015 Neural networks are black box model structures that map inputs to outputs and do not require underlying mathematical models between the two They are frequently used in the field of system identification the area that deals with the development of system models based on input output data In this work a hybrid system identification method is implemented with neural networks NN and the Minimum Model Error estimator MME on different benchmark experimental setups as well as simulations The MME algorithm uses a cost function with a covariance constraint to determine smooth state estimates of a system given noisy measurement data and an assumed model As a byproduct it generates a vector of unmodeled nonlinear or linear system dynamics which can then be modeled by a neural network Combining this neural network with the assumed model from MME a system plant model is obtained The purpose of neural networks in this research is two fold to demonstrate the advantages of combined MME NN models over some common system identification methods and to investigate the feasibility of using the data stored in the network

structure of those models to develop a classification scheme for condition monitoring The approach to classification that is used in this research does not lead to successful implementation of such a scheme Abstract **Nonlinear System Identification with Local Linear Neuro-fuzzy Models** Oliver Nelles, 1999

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