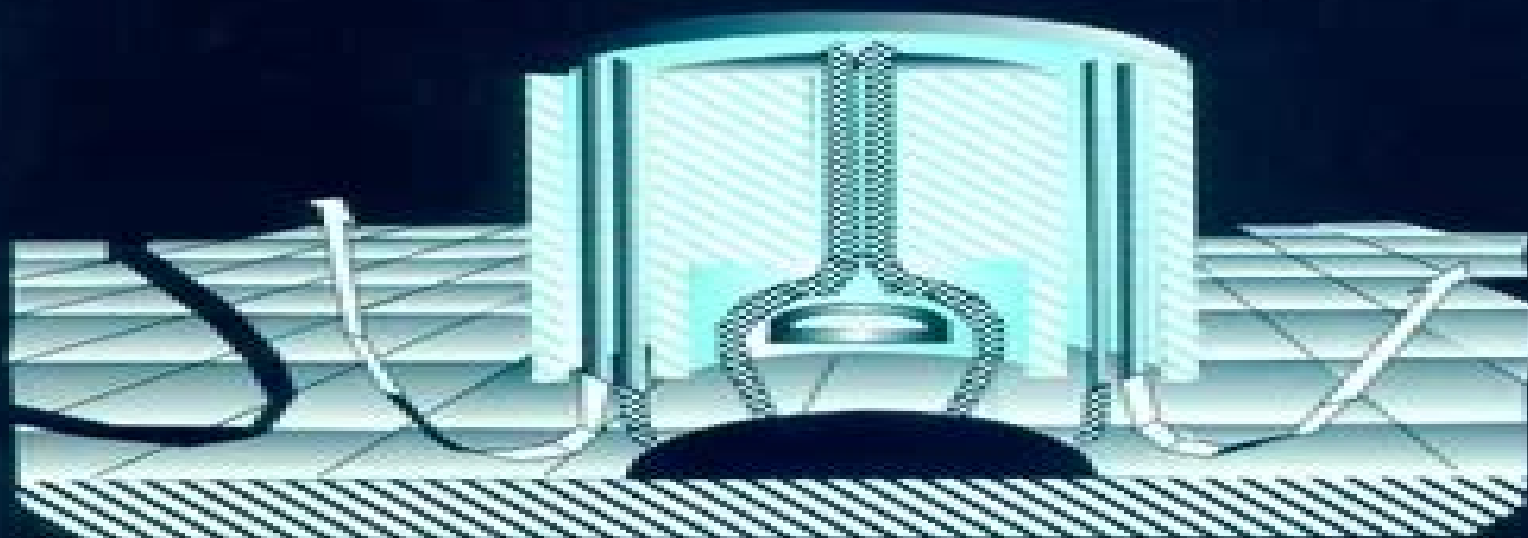


World Scientific Series in Robotics and Intelligent Systems — Vol. 22

ODOUR DETECTION BY MOBILE ROBOTS

R. ANDREW RUSSELL



World Scientific

Odour Detection By Mobile Robots

Brian Lithgow, Irena Cosic



Odour Detection By Mobile Robots:

Odour Detection by Mobile Robots R. Andrew Russell, 1999 Insects are extremely successful creatures thriving in our ever changing Odour Sensing Technology Odour Discrimination Airflow Broadcast Chemical Signals Chemical Markings as Signals Trail Following Coding Information into Trails Heat as a Short Lived Marker Readership Graduate students researchers in robotics mechatronics artificial intelligence

Electronic Nose Technologies and Advances in Machine Olfaction Albastaki, Yousif Abdullatif, Albalooshi, Fatema, 2018-04-13 The design and study of materials is a pivotal component to new discoveries in the various fields of science and technology By better understanding the components and structures of materials researchers can increase its applications across different industries Electronic Nose Technologies and Advances in Machine Olfaction is an academic scholarly resource that examines the emerging applications of odor sensing devices as well as a better understanding of the designing process with the aid of neural networks and various other technologies Featuring coverage on a broad range of topics including food spoilage detection chemical sensing and olfactometer this book is a vital resource for engineers academicians researchers students and practitioners seeking current research on the advancements in applications of odor sensing devices

Essentials of Machine Olfaction and Taste Takamichi Nakamoto, 2016-04-18 Essentials of Machine Olfaction and Taste This book provides a valuable information source for olfaction and taste which includes a comprehensive and timely overview of the current state of knowledge of use for olfaction and taste machines Presents original latest research in the field with an emphasis on the recent development of human interfacing Covers the full range of artificial chemical senses including olfaction and taste from basic through to advanced level Timely project in that mobile robots olfactory displays and odour recorders are currently under research driven by commercial demand

TENCON 2004, 2004

Handbook of Machine Olfaction Tim C. Pearce, 2003 Electronic noses that means instruments which mimic the sense of smell They are very useful for a remarkably variety of applications e g in food and pharmaceutical industry in environmental control or clinical diagnostics The book covers biological and technical fundamentals up to date research contributed by renowned international scientists as well as application oriented news from successful E nose manufacturers It is a unique standard work for scientists in research and development and for users of electronic noses

Olfaction and Electronic Nose Matteo Pardo, Giorgio Sberveglieri, 2009-06-09 ISOEN addresses research in the fields of gas sensors and artificial olfactory systems In this edition we broadened the participation spectrum to all kinds of analytical instrumentation for odor measurement and to biological olfaction We also had a strong involvement in industry The audience comprises materials scientists chemists physicists engineers biologists computer scientists and application specialists e g food medical environmental security

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Proceedings of the National Academy of Sciences of the United States of America National Academy of Sciences (U.S.), 2002

Robotica, 1996

Proceedings of the Intelligent Vehicles ... Symposium, 1995 *Proceedings*, 2000 Proceedings of the 2nd International Conference on Bioelectromagnetism Brian Lithgow, Irena Cosic, 1998 Aimed at equipment designers systems designers and libraries this work is on biomagnetism and biomedical engineering Odour Source Localization Using Multiple Plume-tracing Mobile Robots Zhenzhang Liu, 2010 The recent increasing threat of chemical weapons technologies has highlighted the need for superior detection of hazardous emission sources One promising area of technological development is odour source detection using plume tracing mobile robots which have the potential to detect emissions released by sources such as fire toxic gas and explosives without endangering human life during the detection process Aims of this proposed research project are to investigate the use of multiple mobile robots to locate a dangerous odour source in realistic environments The realistic environments presented in this study are two city like environments and a complicated indoor building environment These two kinds of environments are considered to have a very close relationship with human life The research methods for this project include two aspects which are simulation and experimental validation A simulation framework for this study was constructed using combined CFD and MATLAB techniques The control strategies for plume tracing mobile robots were developed and tested in the simulation framework A prototype plume tracing mobile robot was physically developed for the purpose of real world experimental validation A series of experiments proved that the control strategies developed in the simulation framework was applicable to a real plume tracing robot on the other hand the experiments also proved that the developed simulation framework was capable of reflecting real world plume tracing scenarios The contributions to the plume tracing research field achieved in this research project are a a novel simulation framework using combined CFD and MATLAB techniques for plume tracing research was developed and it is believed that the framework is helpful for the researchers in plume tracing research field b a small size plume tracing mobile robot was fabricated This small robot has the capability of tracing odour plumes in complicated wind varying environments The capability of this kind of robot is considered to be a new input into this research field c a supervisory approach was proposed in this study and the developed supervisory programs coordinated multiple robots to locate an odour source in realistic environments effectively *American Book Publishing Record*, 1999 **Mobile Robotics in Healthcare** Nikos Katevas, 2001 *Autonomous Robotic Systems* Anibal T.de Almeida, 1998-05-26 This book constitutes the presentations made at the Advanced Research Workshop on Autonomous Robotic Systems which was held at the University of Coimbra Portugal June 1997 The aim of the meeting was to bring together leading researchers in the area of autonomous systems for mobility and manipulation and the aim of this book is to share the presentations with the reader The book presents the most recent developments in the field Topics include sensors and navigation in mobile robots robot co operation telerobotics legged robots climbing robots and applications Existing and emerging applications of autonomous systems are described in great detail including applications in forestry cleaning mining tertiary buildings assistance to the elderly and handicapped

and surgery The chapters are written in a structured and advanced tutorial style by leading specialists from Europe Australia Japan and USA The style will allow the reader to grasp the state of the art and research directions in the area of autonomous systems Navigating Mobile Robots Johann Borenstein,H. R. Everett,Liqiang Feng,1996 Sensors for mobile robot positioning Systems and menthods for mobile robot positioning **Subject Guide to Books in Print** ,1991 *Proceedings of 1995 IEEE International Conference on Robotics and Automation, May 21-27, 1995, Nagoya, Aichi, Japan* ,1995
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